

Course code	Course Name	L-T-P - Credits	Year of Introduction
EE302	ELECTROMAGNETICS	2-1-0-3	2016
<b>Prerequisite: Nil</b>			
<b>Course Objectives</b> <ul style="list-style-type: none"> <li>To develop a conceptual basis of electrostatics, magnetostatics, electromagnetic waves</li> <li>To understand various engineering applications of electromagnetics</li> </ul>			
<b>Syllabus</b> Introduction to vector calculus, Electrostatics, Electrical potential, energy density and their applications. Magneto statics, magnetic flux density, scalar and vector potential and its applications, Time varying electric and magnetic fields, Electromagnetic waves			
<b>Expected outcome .</b> The students will be able to: <ol style="list-style-type: none"> <li>Analyze fields and potentials due to static charges</li> <li>Explain the physical meaning of the differential equations for electrostatic and magnetic fields</li> <li>Understand how materials are affected by electric and magnetic fields</li> <li>Understand the relation between the fields under time varying situations</li> <li>Understand principles of propagation of uniform plane waves.</li> <li>Be aware of electromagnetic interference and compatibility</li> </ol>			
<b>Text Book:</b> <ol style="list-style-type: none"> <li>Nannapeni Narayana Rao, "Elements of Engineering Electromagnetics", Prentice Hall India</li> <li>Sadiku M. N. O, <i>Elements of Electromagnetics</i>, Oxford university Press, 2010</li> </ol>			
<b>Data Book ( Approved for use in the examination):</b>			
<b>References:</b> <ol style="list-style-type: none"> <li>Cheng D. K., Field and Wave Electromagnetic, Pearson Education, 2013.</li> <li>Edminister J. A., Electromagnetics, Schaum Outline Series , Tata McGraw-Hill, 2006.</li> <li>Gangadhar K. A. and P. M. Ramanathan , Electromagnetic field theory , Khanna Publishers, 2009.</li> <li>Hayt W. H. and J. A. Buck , Engineering Electromagnetics, 8/e, McGraw-Hill, 2012.</li> <li>Inan U. S. and A. S. Inan, Engineering Electromagnetics, Pearson Education, 2010.</li> <li>John Krauss and Daniel A. Fleisch, Electromagnetics with Applications, McGraw-Hill, 5<sup>th</sup> edition</li> <li>Murthy T. V. S. A, Electromagnetic field, S. Chand Ltd, 2008.</li> <li>Premlet B., Electromagnetic theory with applications, Phasor Books, 2000.</li> <li>S.C.Mahapatra and Sudipta Mahapatra ,Principles of Electromagnetics, McGraw-Hill, 2015</li> </ol>			
<b>Course Plan</b>			
Module	Contents	Hours	Sem. Exam Marks
I	<b>STATIC ELECTRIC FIELDS:</b> Introduction to Co-ordinate System – Rectangular – Cylindrical and Spherical Co- ordinate System – Gradient of a Scalar field, Divergence of a Vector field and Curl of a Vector field- Their Physical interpretation. Divergence Theorem, Stokes' Theorem. Numerical problems	6	15%
II	Coulomb's Law, Electric field intensity. Field due to a line charge, Sheet Charge and Continuous Volume Charge distribution. Electric Flux and Flux Density; Gauss's law and its application. Electric Potential-The Potential Gradient. The Electric dipole. The Equipotential surfaces. Capacitance - capacitance of co-axial cable, two wire line. Poisson's and Laplace's equations	8	15%
<b>FIRST INTERNAL EXAMINATION</b>			

<b>III</b>	STATIC MAGNETIC FIELD: Biot-Savart Law, Amperes Force Law.– Magnetic Field intensity due to a finite and infinite wire carrying a current–Magnetic field intensity on the axis of a circular and rectangular loop carrying a current –Magnetic vector potential, Magnetic flux Density and Ampere’s circuital law and simple applications.	6	15%
<b>IV</b>	ELECTRIC AND MAGNETIC FIELDS IN MATERIALS–Electric Polarization–Nature of dielectric materials–Electrostatic energy and energy density–Boundary conditions for electric fields and magnetic fields–Conduction current and displacement current densities–continuity equation for current. Maxwell’s Equation in Differential and integral form from Modified form of Ampere’s circuital law, Faraday’s Law and Gauss Law	8	15%
<b>SECOND INTERNAL EXAMINATION</b>			
<b>V</b>	TIME VARYING ELECTRIC AND MAGNETIC FIELDS: Poynting Vector and Poynting Theorem – Power flow in a co-axial cable – Complex Average Poynting Vector. ELECTROMAGNETIC WAVES: Wave Equation from Maxwell's Equation – Uniform Plane Waves –Wave equation in Phasor form	7	20%
<b>VI</b>	Plane waves propagation in loss less and lossy dielectric medium and conducting medium. Plane wave in good conductor, surface resistance, Skin depth, Intrinsic Impedance and Propagation Constant in all medium. Phase and group velocity. Transmission lines: waves in transmission line –solution for loss less lines –characteristic impedance – VSWR – impedance matching. Introduction to Electromagnetic interference and compatibility.	7	20%
<b>END SEMESTER EXAM</b>			

### QUESTION PAPER PATTERN:

Maximum Marks: 100

Exam Duration: 3Hours.

**Part A:** 8 compulsory questions.

One question from each module of Modules I - IV; and two each from Module V & VI.

Student has to answer all questions. (8 x 5)=40

**Part B:** 3 questions uniformly covering Modules I & II. Student has to answer any 2 from the 3 questions: (2 x 10) =20. Each question can have maximum of 4 sub questions (a,b,c,d), if needed.

**Part C:** 3 questions uniformly covering Modules III & IV. Student has to answer any 2 from the 3 questions: (2 x 10) =20. Each question can have maximum of 4 sub questions (a,b,c,d), if needed.

**Part D:** 3 questions uniformly covering Modules V & VI. Student has to answer any 2 from the 3 questions: (2 x 10) =20. Each question can have maximum of 4 sub questions (a,b,c,d), if needed.

Course code	Course Name	L-T-P -Credits	Year of Introduction
EE304	Advanced Control Theory	3-1-0-4	2016
<b>Prerequisite:</b> EE303 Linear control systems			
<b>Course Objectives:</b> <ul style="list-style-type: none"> <li>To provide a strong concept on the compensator design and on advanced control system analysis and design techniques</li> <li>To analyse the behaviour of discrete time systems and nonlinear control systems.</li> </ul>			
<b>Syllabus:</b> Compensator design-Frequency domain approach-root locus method-Tuning of P, PI and PID controller-State space analysis of systems-state feedback controller design-sampled data control systems-Nonlinear systems-describing function-phase plane-Lyapunov method.			
<b>Expected outcome.</b> On successful completion, students will have the ability to <ol style="list-style-type: none"> <li>design compensators using classical techniques.</li> <li>analyse both linear and nonlinear system using state space methods.</li> <li>analyse the stability of discrete system and nonlinear system.</li> </ol>			
<b>Text Book:</b> <ol style="list-style-type: none"> <li>Hassan K Khalil, Nonlinear Systems, Prentice - Hall International (UK), 2002.</li> <li>Kuo B.C, Analysis and Synthesis of Sampled Data Systems, Prentice Hall Publications.</li> <li>Nagarath I. J. and Gopal M., Control System Engineering, Wiley Eastern, 2008.</li> <li>Nise N. S., Control Systems Engineering, 6/e, Wiley Eastern, 2010.</li> <li>Ogata K., Modern Control Engineering, Prentice Hall of India, New Delhi, 2010.</li> </ol>			
<b>Data Book ( Approved for use in the examination):</b>			
<b>References:</b> <ol style="list-style-type: none"> <li>Alberto Isidori, Nonlinear Control Systems, Springer Verlag, 1995.</li> <li>Gibson J. E., F.B. Tuteur and J. R. Ragazzini, Control System Components, Tata McGraw Hill, 2013</li> <li>Gopal M., Control Systems Principles and Design, Tata McGraw Hill, 2008.</li> <li>Jean-Jacques E. Slotine &amp; Weiping Li, Applied Nonlinear Control, Prentice-Hall., NJ, 1991.</li> </ol>			
<b>Course Plan</b>			
Module	Contents	Hours	Sem. Exam Marks
I	Types of controller- Feedforward-feedback-cascade-P, PI and PID. Compensator design: Realization of compensators – lag, lead and lag-lead -Design of compensator using bode plot.	7	15%
II	Compensator design: Realization of compensators – lag, lead and lag-lead. Design of compensator using rootlocus. Design of P, PI and PID controller using Ziegler-Nichols tuning method.	7	15%
<b>FIRST INTERNAL EXAMINATION</b>			
III	State space analysis of systems: Introduction to state concept - state equation of linear continuous time systems, matrix representation of state equations. Phase variable and canonical forms of state representation-controllable, observable, diagonal	7	15%

	and Jordan canonical forms- solution of time invariant autonomous systems, forced system-state transition matrix-relationship between state equations and transfer function. Properties of state transition matrix-Computation of state transition matrix using Laplace transform-Cayley-Hamilton method. Conversion from canonical form to phase variable form.		
<b>IV</b>	State feedback controller design: Controllability & observability. State feed-back design via pole placement technique. Sampled data control system: Pulse Transfer function-Stability of sampled data system -Routh Hurwitz criterion and Jury's test. Introduction to state-space representation of sampled data systems.	7	15%
<b>SECOND INTERNAL EXAMINATION</b>			
<b>V</b>	Nonlinear systems: Introduction - characteristics of nonlinear systems. Types of nonlinearities. Analysis through harmonic linearisation - Determination of describing function of nonlinearities (relay, dead zone and saturation only) - application of describing function for stability analysis of autonomous system with single nonlinearity.	7 hrs	20%
<b>VI</b>	Phase Plane Analysis: Concepts- Construction of phase trajectories for nonlinear systems and linear systems with static nonlinearities - Singular points – Classification of singular points. Definition of stability- asymptotic stability and instability Liapunov methods to stability of linear and nonlinear, continuous time systems.	7 hrs	20%
<b>END SEMESTER EXAM</b>			

### QUESTION PAPER PATTERN:

Maximum Marks: 100

Exam Duration: 3Hours.

**Part A:** 8 compulsory questions.

One question from each module of Modules I - IV; and two each from Module V & VI.

Student has to answer all questions. (8 x5)=40

**Part B:** 3 questions uniformly covering Modules I & II. Student has to answer any 2 from the 3 questions: (2 x 10) =20. Each question can have maximum of 4 sub questions (a,b,c,d), if needed.

**Part C:** 3 questions uniformly covering Modules III & IV. Student has to answer any 2 from the 3 questions: (2 x 10) =20. Each question can have maximum of 4 sub questions (a,b,c,d), if needed.

**Part D:** 3 questions uniformly covering Modules V & VI. Student has to answer any 2 from the 3 questions: (2 x 10) =20. Each question can have maximum of 4 sub questions (a,b,c,d), if needed.



Course code	Course Name	L-T-P - Credits	Year of Introduction
EE306	POWER SYSTEM ANALYSIS	3-0-0-3	2016
<b>Prerequisite: Nil</b>			
<b>Course Objectives</b> <ul style="list-style-type: none"> <li>To enable the students to analyse power systems under normal and abnormal conditions.</li> <li>To understand the need for load flow analysis and different methods</li> <li>To understand power system modeling</li> <li>To understand the need for stability studies and their analysis</li> </ul>			
<b>Syllabus</b> Per unit quantities - modeling of power system components - methods of analyzing faults in symmetrical and unsymmetrical case - load flow studies - Automatic Generation Control - Automatic voltage control – Economic load dispatch - Unit commitment - Power system stability - Solution of swing equation - Methods of improving stability limits			
<b>Expected outcome .</b> The students will be able to: <ol style="list-style-type: none"> <li>Analyse power systems under normal and abnormal conditions.</li> <li>Carry out load flow studies under normal and abnormal conditions</li> </ol>			
<b>References:</b> <ol style="list-style-type: none"> <li>Cotton H. and H. Barber, <i>Transmission &amp; Distribution of Electrical Energy</i>, 3/e, Hodder and Stoughton, 1978.</li> <li>Gupta B. R., <i>Power System Analysis and Design</i>, S. Chand, New Delhi, 2006.</li> <li>Gupta J.B., <i>Transmission &amp; Distribution of Electrical Power</i>, S.K. Kataria &amp; Sons, 2009.</li> <li>Hadi Saadat, <i>Power System Analysis</i>, 2/e, McGraw Hill, 2002.</li> <li>Kothari D. P. and I. J. Nagrath, <i>Modern Power System Analysis</i>, 2/e, TMH, 2009.</li> <li>Kundur P., <i>Power system Stability and Control</i>, McGraw Hill, 199</li> <li>Soni, M.L., P. V. Gupta and U. S. Bhatnagar, <i>A Course in Electrical Power</i>, Dhanpat Rai &amp; Sons, New Delhi, 1984.</li> <li>Stevenson W. D., <i>Elements of Power System Analysis</i>, 4/e, McGraw Hill, 1982.</li> <li>Uppal S. L. and S. Rao, <i>Electrical Power Systems</i>, Khanna Publishers, 2009.</li> <li>Wadhwa C. L., <i>Electrical Power Systems</i>, 33/e, New Age International, 2004.</li> <li>Weedy B. M., B. J. Cory, N. Jenkins, J. B. Ekanayake and G. Strbac, <i>Electric Power System</i>, John Wiley &amp; Sons, 2012.</li> </ol>			
<b>Course Plan</b>			
Module	Contents	Hours	Sem. Exam Marks
<b>I</b>	Per unit quantities-single phase and three phase-selection of base quantities -advantages of per unit system –changing the base of per unit quantities-Simple problems.	2	15%
	Modelling of power system components - single line diagram – per unit quantities. Symmetrical components- sequence impedances and sequence networks of generators, transformers and transmission lines.	3	
<b>II</b>	Methods of analyzing faults in symmetrical and unsymmetrical case- effects of faults - Power system faults - symmetrical faults - short circuit MVA - current limiting reactors-	8	15%

	Unsymmetrical faults - single line to ground, line to line, double line to ground faults -consideration of prefault current-problems.		
<b>FIRST INTERNAL EXAMINATION</b>			
<b>III</b>	Load flow studies – Introduction-types-network model formulation - formation of bus impedance and admittance matrix, Gauss-Siedel (two iterations), Newton-Raphson (Qualitative analysis only) and Fast Decoupled method (two iterations) - principle of DC load flow.	8	15%
<b>IV</b>	Automatic Generation Control: Load frequency control: single area and two area systems - Automatic voltage control.	6	15%
<b>SECOND INTERNAL EXAMINATION</b>			
<b>V</b>	Economic Operation - Distribution of load between units within a plant - transmission loss as a function of plant generation - distribution of load between plants - Method of computing penalty factors and loss coefficients.	5	20%
	Unit commitment: Introduction — Constraints on unit commitments: Spinning reserve, Thermal unit constraints-Hydro constraints. -	2	
<b>VI</b>	Power system stability - steady state, dynamic and transient stability-power angle curve-steady state stability limit	3	20%
	Mechanics of angular motion-Swing equation – Solution of swing equation - Point by Point method - RK method - Equal area criterion application - Methods of improving stability limits.	5	
<b>END SEMESTER EXAM</b>			

**QUESTION PAPER PATTERN:**

Maximum Marks: 100

Exam Duration: 3Hours.

**Part A:** 8 compulsory questions.

One question from each module of Modules I - IV; and two each from Module V & VI.

Student has to answer all questions. (8 x5)=40

**Part B:** 3 questions uniformly covering Modules I & II. Student has to answer any 2 from the 3 questions: (2 x 10) =20. Each question can have maximum of 4 sub questions (a,b,c,d), if needed.

**Part C:** 3 questions uniformly covering Modules III & IV. Student has to answer any 2 from the 3 questions: (2 x 10) =20. Each question can have maximum of 4 sub questions (a,b,c,d), if needed.

**Part D:** 3 questions uniformly covering Modules V & VI. Student has to answer any 2 from the 3 questions: (2 x 10) =20. Each question can have maximum of 4 sub questions (a,b,c,d), if needed.

Course code	Course Name	L-T-P-Credits	Year of Introduction
EE308	Electric Drives	3-0-0-3	2016
<b>Prerequisite:</b> EE202 & EE205			
<b>Course Objectives</b> <ul style="list-style-type: none"> <li>To provide fundamental knowledge in dynamics and control of Electric Drives.</li> <li>To justify the selection of Drives for various applications.</li> <li>To familiarize the various semiconductor controlled drives employing various motors.</li> </ul>			
<b>Syllabus</b> Fundamentals of dynamics and control of electric drives– separately excited dc motor drives using controlled rectifiers – chopper controlled dc drives – ac voltage controllers – three phase induction motor speed control – VSI and CSI fed induction motor drives – synchronous motor drives			
<b>Expected outcome.</b> The students will be able to select a drive for a particular application. They will familiarize with the various control techniques employed for controlling drives with ac and dc motors.			
<b>Text books</b> <ol style="list-style-type: none"> <li>Bimal K. Bose “Modern power electronics and AC drives” Pearson Education, Asia 2003</li> <li>Dubey G. K. “Power semiconductor control drives” Prentice Hall, Englewood Cliffs, New Jersey, 1989</li> </ol>			
<b>References:</b> <ol style="list-style-type: none"> <li>Dewan S.B. , G. R. Slemon, A. Strauven, “Power semiconductor drives”, John Wiley and sons</li> <li>Dr. P. S. Bimbira “Power electronics”, Khanna publishers</li> <li>J. M. D. Murphy “Thyristor control of AC drives”</li> <li>N. K. De, P. K. Sen “Electric drives” Prentice Hall of India 2002</li> <li>Ned Mohan, Tore m Undeland, William P Robbins, “Power electronics converters applications and design”, John Wiley and Sons.</li> <li>Pillai S. K. “A first course on electric drives”, Wilely Eastern Ltd, New Delhi</li> <li>Vedam Subrahmanyam, “Electric Drives”, MC Graw Hill Education, New Delhi</li> <li>W. Shepherd, L. N. Hulley and D. T. Liang, “Power Electronocs and motor control”, Second Edition, Cambridge University Press, 1995.</li> </ol>			
<b>Course Plan</b>			
Module	Contents	Hours	Sem. Exam Marks
I	Introduction to electric drives – Block diagram – advantages of electric drives – Dynamics of motor load system, fundamental equations, and types of load – classification of load torque, four quadrant operation of drives. Steady state stability. Introduction to closed loop control of drives.	7	15%
II	DC motor drives- constant torque and constant power operation, separately excited dc motor drives using controlled rectifiers, single phase semi converter and single phase fully controlled converter drives. Three phase semi converter and fully controlled converter drives. Dual converters, applications of dual converter for speed control of DC motor. Closed loop control of separately excited dc motor drive. DC series motor drive for traction application.	7	15%
<b>FIRST INTERNAL EXAMINATION</b>			

<b>III</b>	Chopper controlled DC drives. Analysis of single quadrant chopper drives. Regenerative braking control. Two quadrant chopper drives. Four quadrant chopper drives. Cycloconverters for drive applications – different types – basic principle.	7	15%
<b>IV</b>	Three phase induction motor speed control. Using semiconductor devices. Stator voltage control – stator frequency control - Stator voltage and frequency control (v/f). Rotor chopper speed control - slip power recovery control schemes – sub synchronous and super synchronous speed variations.	7	15%
<b>SECOND INTERNAL EXAMINATION</b>			
<b>V</b>	Voltage source inverter fed induction motor drives, Current source inverter fed induction motor drives. Concept of space vector – Basic transformation in reference frame theory – field orientation principle.	7	20%
<b>VI</b>	Synchronous motor drives – introduction to v/f control. Permanent Magnet synchronous motor drives – different types – control requirements, converter circuits, modes of operation. Microcontroller based permanent magnet synchronous motor drives (schematic only).	7	20%
<b>END SEMESTER EXAM</b>			

### QUESTION PAPER PATTERN:

Maximum Marks: 100

Exam Duration: 3Hours.

**Part A:** 8 compulsory questions.

One question from each module of Modules I - IV; and two each from Module V & VI.

Student has to answer all questions. (8 x5)=40

**Part B:** 3 questions uniformly covering Modules I & II. Student has to answer any 2 from the 3 questions: (2 x 10) =20. Each question can have maximum of 4 sub questions (a,b,c,d), if needed.

**Part C:** 3 questions uniformly covering Modules III & IV. Student has to answer any 2 from the 3 questions: (2 x 10) =20. Each question can have maximum of 4 sub questions (a,b,c,d), if needed.

**Part D:** 3 questions uniformly covering Modules V & VI. Student has to answer any 2 from the 3 questions: (2 x 10) =20. Each question can have maximum of 4 sub questions (a,b,c,d), if needed.



Course code	Course Name	L-T-P - Credits	Year of Introduction
HS300	Principles of Management	3-0-0-3	2016
<b>Prerequisite : Nil</b>			
<b>Course Objectives</b> <ul style="list-style-type: none"> <li>To develop ability to critically analyse and evaluate a variety of management practices in the contemporary context;</li> <li>To understand and apply a variety of management and organisational theories in practice;</li> <li>To be able to mirror existing practices or to generate their own innovative management competencies, required for today's complex and global workplace;</li> <li>To be able to critically reflect on ethical theories and social responsibility ideologies to create sustainable organisations.</li> </ul>			
<b>Syllabus</b> Definition, roles and functions of a manager, management and its science and art perspectives, management challenges and the concepts like, competitive advantage, entrepreneurship and innovation. Early contributors and their contributions to the field of management. Corporate Social Responsibility. Planning, Organizing, Staffing and HRD functions, Leading and Controlling. Decision making under certainty, uncertainty and risk, creative process and innovation involved in decision making.			
<b>Expected outcome.</b> A student who has undergone this course would be able to <ol style="list-style-type: none"> <li>manage people and organisations</li> <li>critically analyse and evaluate management theories and practices</li> <li>plan and make decisions for organisations</li> <li>do staffing and related HRD functions</li> </ol>			
<b>Text Book:</b> Harold Koontz and Heinz Weihrich, <i>Essentials of Management</i> , McGraw Hill Companies, 10th Edition.			
<b>References:</b> <ol style="list-style-type: none"> <li>Daft, <i>New era Management</i>, 11th Edition, Cengage Learning</li> <li>Griffin, <i>Management Principles and Applications</i>, 10th Edition, Cengage Learning</li> <li>Heinz Weirich, Mark V Cannice and Harold Koontz, <i>Management: a Global, Innovative and Entrepreneurial Perspective</i>, McGraw Hill Education, 14th Edition</li> <li>Peter F Drucker, <i>The Practice of Management</i>, McGraw Hill, New York</li> <li>Robbins and Coulter, <i>Management</i>, 13th Edition, 2016, Pearson Education</li> </ol>			
<b>Course Plan</b>			
Module	Contents	Hours	Sem. Exam Marks
I	Introduction to Management: definitions, managerial roles and functions; Science or Art perspectives- External environment-global, innovative and entrepreneurial perspectives of Management (3 Hrs.)– Managing people and organizations in the context of New Era- Managing for competitive advantage - the Challenges of Management (3 Hrs.)	6	15%

<b>II</b>	<b>Early Contributions and Ethics in Management:</b> Scientific Management- contributions of Taylor, Gilbreths, Human Relations approach-contributions of Mayo, McGregor's Theory, Ouchi's Theory Z (3 Hrs.) Systems Approach, the Contingency Approach, the McKinsey 7-S Framework Corporate Social responsibility- Managerial Ethics. (3 Hrs)	6	15%
<b>FIRST INTERNAL EXAMINATION</b>			
<b>III</b>	<b>Planning:</b> Nature and importance of planning, -types of plans (3 Hrs.)- Steps in planning, Levels of planning - The Planning Process. – MBO (3 Hrs.).	6	15%
<b>IV</b>	<b>Organising for decision making:</b> Nature of organizing, organization levels and span of control in management Organisational design and structure –departmentation, line and staff concepts (3 Hrs.) Limitations of decision making- Evaluation and selecting from alternatives- programmed and non programmed decisions - decision under certainty, uncertainty and risk-creative process and innovation (3 Hrs.)	6	15%
<b>SECOND INTERNAL EXAMINATION</b>			
<b>V</b>	<b>Staffing and related HRD Functions:</b> definition, Empowerment, staff – delegation, decentralization and recentralisation of authority – Effective Organizing and culture-responsive organizations –Global and entrepreneurial organizing (3 Hrs.) Manager inventory chart-matching person with the job-system approach to selection (3 Hrs.) Job design-skills and personal characteristics needed in managers-selection process, techniques and instruments (3 Hrs.)	9	20%
<b>VI</b>	<b>Leading and Controlling:</b> Leading Vs Managing – Trait approach and Contingency approaches to leadership - Dimensions of Leadership (3 Hrs.) - Leadership Behavior and styles – Transactional and Transformational Leadership (3 Hrs.) Basic control process- control as a feedback system – Feed Forward Control – Requirements for effective control – control techniques – Overall controls and preventive controls – Global controlling (3 Hrs.)	9	20%
<b>END SEMESTER EXAM</b>			

#### Question Paper Pattern

Max. marks: 100, Time: 3 hours .

The question paper shall consist of three parts

**Part A:** 4 questions uniformly covering modules I and II. Each question carries 10 marks

Students will have to answer any three questions out of 4 (3X10 marks =30 marks)

**Part B :** 4 questions uniformly covering modules III and IV. Each question carries 10 marks

Students will have to answer any three questions out of 4 (3X10 marks =30 marks)

**Part C:** 6 questions uniformly covering modules V and VI. Each question carries 10 marks

Students will have to answer any four questions out of 6 (4X10 marks =40 marks)

**Note:** In all parts, each question can have a maximum of four sub questions, if needed.

Course code	Course Name	L-T-P - Credits	Year of Introduction
EE362	Data Structures and Algorithms	3-0-0-3	2016
<b>Prerequisite:</b> EE207 Computer programming			
<b>Course Objectives</b> <ul style="list-style-type: none"> <li>To introduce the fundamental concept of data structures and to emphasize the importance of data structures in developing and implementing efficient algorithms</li> <li>To impart knowledge about algorithm specification</li> </ul>			
<b>Syllabus</b> Linear Structures , Tree Structures , Applications of trees , Balanced Search Trees and Indexing , Graphs , Shortest-path algorithms , Applications of graphs , Algorithm Design , Algorithm Analysis , Dynamic programming			
<b>Expected outcome.</b> The students will be able to: <ol style="list-style-type: none"> <li>Describe how arrays, records, linked structures, stacks, queues, trees, and graphs are represented in memory and used by algorithms</li> <li>Describe common applications for arrays, records, linked structures, stacks, queues, trees, and graphs</li> <li>Write programs that use arrays, records, linked structures, stacks, queues, trees, and graphs</li> <li>Demonstrate different methods for traversing trees</li> <li>Compare alternative implementations of data structures with respect to performance</li> <li>Compare and contrast the benefits of dynamic and static data structures implementations</li> <li>Describe the concept of recursion, give examples of its use, describe how it can be implemented using a stack</li> </ol>			
<b>Text Book:</b> <ol style="list-style-type: none"> <li>Robert Kruse, Data Structures and program design in C, Pearson Education Asia</li> <li>Samanta, Classic Data Structures, PHI</li> <li>Trembley &amp; Sorenson, An introduction to Data Structures with applications:, McGraw Hill</li> </ol>			
<b>References:</b> <ol style="list-style-type: none"> <li>Donald E Knuth, The Art of Computer Programming, Vol.1: Fundamental Algorithms, Addison-Wesley, 1997.</li> <li>Langsam, Augenstein &amp; Tanenbaum, Data Structures using C &amp; C++: Pearson, 1995</li> <li>N.Wirth, Algorithms + Data Structures &amp; Programs:, PHI</li> <li>Sahni &amp; Mehta, Fundamentals of Data Structures in C++: Horowitz, , Galgottia Pub.</li> <li>Thomas Standish, Data structures in Java:, Pearson Education Asia</li> </ol>			
Course Plan			
Module	Contents	Hours	Sem. Exam Marks
I	Linear Structures : Abstract data types(ADT), List ADT, Array based implementation, Linked list implementation, Curser based linked lists, Doubly linked lists, Applications of lists, Stack ADT, Queue ADT, Circular queue implementation, Applications of stacks and queues	7	15%

<b>II</b>	Tree Structures : Need for nonlinear structures, Tree ADT, Tree traversals, Left child right sibling data structures for general trees, Binary tree ADT, Expression trees, Applications of trees, Binary search tree ADT	7	15%
<b>FIRST INTERNAL EXAMINATION</b>			
<b>III</b>	Balanced Search Trees and Indexing : AVL trees, Binary heaps, B-trees, Hashing, Separate chaining, Open addressing, Linear probing	7	15%
<b>IV</b>	Graphs : Definitions, Topological sort, Breadth-first traversal, Shortest-path algorithms, Minimum spanning tree, Prim's and Kruskal's algorithms, Depth-first traversal, Bio connectivity, Euler circuits, Applications of graphs	7	15%
<b>SECOND INTERNAL EXAMINATION</b>			
<b>V</b>	Algorithm Design: Greedy algorithm, Divide and conquer, Dynamic programming, Backtracking, Branch and bound, Randomized algorithms	7	20%
<b>VI</b>	Algorithm Analysis : Asymptotic notations, Recurrences, NP complete problems	7	20%
<b>END SEMESTER EXAM</b>			

#### QUESTION PAPER PATTERN:

Maximum Marks: 100

Exam Duration: 3Hours.

**Part A:** 8 compulsory questions.

One question from each module of Modules I - IV; and two each from Module V & VI.

Student has to answer all questions. (8 x5)=40

**Part B:** 3 questions uniformly covering Modules I & II. Student has to answer any 2 from the 3 questions: (2 x 10) =20. Each question can have maximum of 4 sub questions (a,b,c,d), if needed.

**Part C:** 3 questions uniformly covering Modules III & IV. Student has to answer any 2 from the 3 questions: (2 x 10) =20. Each question can have maximum of 4 sub questions (a,b,c,d), if needed.

**Part D:** 3 questions uniformly covering Modules V & VI. Student has to answer any 2 from the 3 questions: (2 x 10) =20. Each question can have maximum of 4 sub questions (a,b,c,d), if needed.



Course code	Course Name	L-T-P - Credits	Year of Introduction
EE364	Switched Mode Power Converters	3-0-0-3	2016
<b>Prerequisite : Nil</b>			
<b>Course Objectives</b> <ul style="list-style-type: none"> <li>To study and analyze various types of switched mode dc- dc converters, inverters and resonant converters and its switching techniques.</li> </ul>			
<b>Syllabus</b> DC-DC convertors without isolation – switched mode power supply – DC-DC converters with isolation – switched mode DC-AC converter – sine PWM and space vector PWM - resonant converter			
<b>Expected outcome.</b> The students will have <ol style="list-style-type: none"> <li>ability to analyze and design switched mode power converters</li> <li>proper understanding about soft switching and its applications</li> <li>deep knowledge in pulse width modulated techniques</li> </ol>			
<b>Text Book:</b> <ol style="list-style-type: none"> <li>Mohan, Undeland, Robbins, <i>Power Electronics – Converters Application and Design</i>, Wiley-India</li> <li>Muhammad H. Rashid, <i>Power Electronics – Circuits, Devices and Applications</i>, Pearson Education</li> </ol>			
<b>References:</b> <ol style="list-style-type: none"> <li>Abraham Pressman, <i>Switching Power supply Design</i>, McGraw Hill</li> </ol>			
<b>Course Plan</b>			
Module	Contents	Hours	Sem. Exam Marks
I	Switched Mode DC-to-DC Converter - buck converters – boost Converter – buck-boost converter - Continuous Conduction mode – design of filter inductance & capacitance - boundary between continuous and discontinuous conduction – critical values of inductance/load resistance - discontinuous conduction mode with constant output voltage - Output voltage ripple	7	15%
II	Cuk converter – Full-ridge dc-dc Converter – PWM with bipolar voltage and unipolar voltage switching –comparison of dc-dc converters - Linear Power Supply – disadvantages of linear power supply – switched mode power supply – dc-dc converters with electrical isolation –unidirectional core excitation & bidirectional core excitation	7	15%
<b>FIRST INTERNAL EXAMINATION</b>			
III	Fly back converter – continuous & discontinuous conduction mode - double ended fly back converter – forward converters – basic forward converter – practical forward converter – continuous conduction mode only - double ended forward converter – push pull converter – half bridge converter – full bridge converter – continuous conduction mode – current source dc-dc converter	7	15%
IV	Switched Mode DC to AC converter – 1-phase square wave full-bridge inverter – square wave switching scheme - sine PWM switching scheme – PWM with bipolar & unipolar voltage switching - harmonic analysis of output voltage – output control by voltage cancellation - 3-phase voltage source inverter – 3-phase sine PWM inverter – RMS line to line voltage & RMS fundamental line-to-line voltage – square wave operation -	8	15%

	Switching utilisation ratio of 1-phase & 3-phase full-bridge inverters		
<b>SECOND INTERNAL EXAMINATION</b>			
<b>V</b>	Concept of space vector – space vector modulation – reference vector & switching times – space vector sequence – comparison of sine PWM & space vector PWM - programmed (selective) harmonic elimination switching – current controlled voltage source inverter - hysteresis current control	6	20%
<b>VI</b>	Resonant Converters - Basic resonant circuit concepts – series resonant circuit – parallel resonant circuit – load resonant converter - ZCS resonant converter - L type & M type - ZVS resonant converter – comparison of ZCS & ZVS Resonant Converters	7	20%
<b>END SEMESTER EXAM</b>			

### QUESTION PAPER PATTERN:

Maximum Marks: 100

Exam Duration: 3Hours.

**Part A:** 8 compulsory questions.

One question from each module of Module I - IV; and two each from Module V & VI.

Student has to answer all questions. (8 x 5)=40

**Part B:** 3 questions uniformly covering Modules I & II. Student has to answer any 2 from the 3 questions: (2 x 10) =20. Each question can have maximum of 4 sub questions (a,b,c,d), if needed.

**Part C:** 3 questions uniformly covering Modules III & IV. Student has to answer any 2 from the 3 questions: (2 x 10) =20. Each question can have maximum of 4 sub questions (a,b,c,d), if needed.

**Part D:** 3 questions uniformly covering Modules V & VI. Student has to answer any 2 from the 3 questions: (2 x 10) =20. Each question can have maximum of 4 sub questions (a,b,c,d), if needed.

Course code	Course Name	L-T-P -Credits	Year of Introduction
EE366	Illumination Technology	3-0-0-3	2016
<b>Prerequisite: Nil</b>			
<b>Course Objectives</b> <ul style="list-style-type: none"> <li>• To provide an introduction to the fundamentals of illumination engineering and architectural lighting design.</li> <li>• To impart lighting fundamentals, measurement, and technology and their application in the analysis and design of architectural lighting systems</li> </ul>			
<b>Syllabus</b> Introduction of Light , Types of illumination , Lighting systems , Lighting Scheme , Measurement of Light , Laws of illumination , Design of Interior Lighting, Determination of Lamp Lumen output taking into account voltage and temperature variations , Indian standard recommendation and standard practices for illumination levels in various areas, Special feature for entrance, staircase, Corridor lighting and industrial building , Design of Outdoor Lighting , Special Features of Aesthetic Lighting			
<b>Expected outcome.</b> The students will be able to: <ol style="list-style-type: none"> <li>Identify the criteria for the selection of lamps and lighting systems for an indoor or outdoor space</li> <li>Perform calculations on photometric performance of light sources and luminaires for lighting design</li> <li>Evaluate different types of lighting designs and applications</li> </ol>			
<b>Text Books</b> <ol style="list-style-type: none"> <li>1. D.C. Pritchard Lighting, Routledge, 2016</li> <li>2. Jack L. Lindsey, Applied Illumination Engineering , PHI, 1991</li> <li>3. John Matthews Introduction to the Design and Analysis of Building Electrical Systems, Springer, 1993</li> <li>4. M.A. Cayless, Lamps and Lighting , Routledge, 1996</li> </ol>			
<b>References:</b> <ol style="list-style-type: none"> <li>1. IS CODE 3646</li> <li>2. IS CODE 6665</li> </ol>			
<b>Course Plan</b>			
Module	Contents	Hours	Sem. Exam Marks
<b>I</b>	Introduction of Light : Types of illumination, Day lighting, Supplementary artificial lighting and total lighting, Quality of good lighting, Factors affecting the lighting-shadow, glare, reflection, Colour rendering and stroboscopic effect, Methods of artificial lighting, Lighting systems-direct, indirect, semi direct, semi indirect, Lighting scheme, General and localised	6	15%
<b>II</b>	Measurement of Light : Definition of luminous flux, Luminous intensity, Lumen, Candle power, Illumination, M.H.C.P, M.S.C.P, M.H.S.C.P, Lamp efficiency, Brightness or luminance, Laws of illumination, Inverse square law and Lambert's Cosine law, Illumination at horizontal and vertical plane from point source, Concept of polar curve, Calculation of luminance and illumination in case of linear source, round source and flat source	7	15%
<b>FIRST INTERNAL EXAMINATION</b>			

<b>III</b>	Design of Interior Lighting : Definitions of maintenance factor, Uniformity ratio, Direct ratio, Coefficients of utilisation and factors affecting it, Illumination required for various work planes, Space to mounting height ratio, Types of fixtures and relative terms used for interior illumination such as DLOR and ULOR, Selection of lamp and luminance, Selection of utilisation factor, reflection factor and maintenance factor Determination of Lamp Lumen output taking into account voltage and temperature variations, Calculation of wattage of each lamp and no of lamps needed, Layout of lamp luminaire, Calculation of space to mounting height ratio, Indian standard recommendation and standard practices for illumination levels in various areas, Special feature for entrance, staircase, Corridor lighting and industrial building	8	15%
<b>IV</b>	Design of Outdoor Lighting : Street Lighting : Types of street and their level of illumination required, Terms related to street and street lighting, Types of fixtures used and their suitable application, Various arrangements in street lighting, Requirements of good street lighting, Selection of lamp and luminaire, Calculation of their wattage, Number and arrangement, Calculation of space to mounting height ratio, Calculation of illumination level available on road	7	15%
<b>SECOND INTERNAL EXAMINATION</b>			
<b>V</b>	Design of Outdoor Lighting : Flood Lighting : Terms related to flood lighting, Types of fixtures and their suitable applications, Selection of lamp and projector, Calculation of their wattage and number and their arrangement, Calculation of space to mounting height ratio, Recommended method for aiming of lamp	7	20%
<b>VI</b>	Special Features of Aesthetic Lighting : Monument and statue lighting, Sports lighting, Hospital lighting, Auditorium lighting	7	20%
<b>END SEMESTER EXAM</b>			

#### QUESTION PAPER PATTERN:

Maximum Marks: 100

Exam Duration: 3Hours.

**Part A:** 8 compulsory questions.

One question from each module of Modules I - IV; and two each from Module V & VI.

Student has to answer all questions. (8 x5)=40

**Part B:** 3 questions uniformly covering Modules I & II. Student has to answer any 2 from the 3 questions: (2 x 10) =20. Each question can have maximum of 4 sub questions (a,b,c,d), if needed.

**Part C:** 3 questions uniformly covering Modules III & IV. Student has to answer any 2 from the 3 questions: (2 x 10) =20. Each question can have maximum of 4 sub questions (a,b,c,d), if needed.

**Part D:** 3 questions uniformly covering Modules V & VI. Student has to answer any 2 from the 3 questions: (2 x 10) =20. Each question can have maximum of 4 sub questions (a,b,c,d), if needed.



Course code	Course Name	L-T-P - Credits	Year of Introduction
EE368	SOFT COMPUTING	3-0-0-3	2016
<b>Prerequisite: Nil</b>			
<b>Course Objectives</b> <ul style="list-style-type: none"> <li>To provide the students with the concepts of soft computing techniques such as neural networks, fuzzy systems, genetic algorithms</li> </ul>			
<b>Syllabus</b> Introduction to Soft Computing and Neural Networks , Fuzzy Sets and Fuzzy Logic: Fuzzy Sets, Neuro-Fuzzy Modelling , Machine Learning , Machine Learning Approach to Knowledge Acquisition			
<b>Expected outcome.</b> The students will be able to get an idea on : <ol style="list-style-type: none"> <li>Artificial Intelligence, Various types of production systems, characteristics of production systems.</li> <li>Neural Networks, architecture, functions and various algorithms involved.</li> <li>Fuzzy Logic, Various fuzzy systems and their functions.</li> <li>Genetic algorithms, its applications and advances</li> <li>The unified and exact mathematical basis as well as the general principles of various soft computing techniques.</li> </ol>			
<b>Text Book:</b> <ol style="list-style-type: none"> <li>Digital Neural Network -S.Y Kung , Prentice-Hall of India</li> <li>James A. Freeman and David M. Skapura, “Neural Networks Algorithms, Applications, and Programming Techniques”, Pearson Edn.,</li> <li>Jyh-Shing Roger Jang, Chuen-Tsai Sun, Eiji Mizutani, “Neuro-Fuzzy and Soft Computing”, Prentice-Hall of India,</li> </ol>			
<b>References:</b> <ol style="list-style-type: none"> <li>Amit Konar, “Artificial Intelligence and Soft Computing”, First Edition,CRC Press, 2000.</li> <li>David E. Goldberg, Genetic Algorithms in Search, Optimization and Machine Learning”, Addison Wesley</li> <li>George J. Klir and Bo Yuan, “Fuzzy Sets and Fuzzy Logic-Theory and Applications”, Prentice Hall</li> <li>Mitchell Melanie, “An Introduction to Genetic Algorithm”, Prentice Hall, 1998.</li> <li>Simon Haykin, “Neural Networks: A Comprehensive Foundation”, Prentice Hall,</li> </ol>			
<b>Course Plan</b>			
Module	Contents	Hours	Sem. Exam Marks
<b>I</b>	Introduction To Soft Computing And Neural Networks : Evolution of Computing - Soft Computing Constituents – From Conventional AI to Computational Intelligence - Adaptive Networks – Feed forward Networks – Supervised Learning	7	15%
<b>II</b>	Neural Networks – Radia Basis Function Networks - Reinforcement Learning – Unsupervised Learning Neural Networks – Adaptive Resonance architectures. Fuzzy Sets And Fuzzy Logic: Fuzzy Sets – Operations on Fuzzy Sets – Fuzzy Relations - Fuzzy Rules and Fuzzy Reasoning	7	15%
<b>FIRST INTERNAL EXAMINATION</b>			
<b>III</b>	Fuzzy Inference Systems – Fuzzy Logic – Fuzzy Expert Systems – Fuzzy Decision Making Neuro-Fuzzy Modeling : Adaptive Neuro-Fuzzy Inference Systems – Coactive Neuro-Fuzzy Modeling – Classification and Regression Trees	7	15%

<b>IV</b>	Data Clustering Algorithms – Rulebase Structure Identification Neuro-Fuzzy Control.	7	15%
<b>SECOND INTERNAL EXAMINATION</b>			
<b>V</b>	Machine Learning : Machine Learning Techniques – Machine Learning Using Neural Nets – Genetic Algorithms (GA)	7	20%
<b>VI</b>	Applications of GA in Machine Learning - Machine Learning Approach to Knowledge Acquisition. Support Vector Machines for Learning – Linear Learning Machines – Support Vector Classification – Support Vector Regression - Applications.	7	20%
<b>END SEMESTER EXAM</b>			

### QUESTION PAPER PATTERN:

Maximum Marks: 100

Exam Duration: 3Hours.

**Part A:** 8 compulsory questions.

One question from each module of Modules I - IV; and two each from Module V & VI.

Student has to answer all questions. (8 x5)=40

**Part B:** 3 questions uniformly covering Modules I & II. Student has to answer any 2 from the 3 questions: (2 x 10) =20. Each question can have maximum of 4 sub questions (a,b,c,d), if needed.

**Part C:** 3 questions uniformly covering Modules III & IV. Student has to answer any 2 from the 3 questions: (2 x 10) =20. Each question can have maximum of 4 sub questions (a,b,c,d), if needed.

**Part D:** 3 questions uniformly covering Modules V & VI. Student has to answer any 2 from the 3 questions: (2 x 10) =20. Each question can have maximum of 4 sub questions (a,b,c,d), if needed.

Course code	Course Name	L-T-P - Credits	Year of Introduction
EE372	Biomedical Instrumentation	3-0-0-3	2016
<b>Prerequisite: Nil</b>			
<b>Course Objectives</b> <ul style="list-style-type: none"> <li>To give a brief introduction to human physiology and various instrumentations system for measurement and analysis of physiological parameters.</li> </ul>			
<b>Syllabus:</b> Development of biomedical instrumentation, Sources of bioelectric potentials, Bio potential electrodes, Electro-conduction system of the heart, Measurement of blood pressure, Measurement of heart sounds, Cardiac pacemakers, defibrillators, Electro encephalogram, Muscle response, Respiratory parameters, Therapeutic Equipments, Imaging Techniques, Instruments for clinical laboratory, Electrical safety, tele- medicine			
<b>Expected outcome.</b>			
<b>Text Book:</b> <ol style="list-style-type: none"> <li>J. G. Webster, Medical Instrumentation, Application and Design, John Wiley and Sons</li> <li>L. Cromwell, F. J. Weibell and L. A. Pfeiffer, Biomedical Instrumentation Measurements, Pearson education, Delhi, 1990.</li> </ol>			
<b>References:</b> <ol style="list-style-type: none"> <li>R. S. Khandpur, Handbook of Biomedical Instrumentation, Tata Mc Graw Hill</li> <li>J. J. Carr and J. M. Brown, Introduction to Biomedical Equipment Technology, Pearson Education</li> </ol>			
<b>Course Plan</b>			
Module	Contents	Hours	Sem. Exam Marks
I	Development of biomedical instrumentation, biometrics, man instrument system components block diagram, physiological systems of the body (brief discussion on Heart and cardio vascular system, Anatomy of nervous system, Physiology of respiratory systems) problems encountered in biomedical measurements. Sources of bioelectric potentials – resting and action potentials - propagation of action potentials – bio electric potentials example (ECG, EEG, EMG, ERG, EOG,EGG etc.)	7	15%
II	Bio potential electrodes – theory – microelectrodes – skin surface electrodes – needle electrodes – biochemical transducers – transducers for biomedical applications. Electro-conduction system of the heart. Electro cardiography – electrodes and leads – Einthoven triangle, ECG read out devices, ECG machine – block diagram.	7	15%
<b>FIRST INTERNAL EXAMINATION</b>			
III	Measurement of blood pressure – direct and indirect measurement – oscillometric measurement –ultrasonic method, measurement of blood flow and cardiac output, plethysmography –photo electric and impedance plethysmographs Measurement of heart sounds –phonocardiography.	7	15%

<b>IV</b>	Cardiac pacemakers – internal and external pacemakers, defibrillators. Electro encephalogram –neuronal communication – EEG measurement. Muscle response– Electromyogram (EMG) – Nerve Conduction velocity measurements- Electromyogram Measurements. Respiratory parameters – Spiro meter, pneumograph	7	15%
<b>SECOND INTERNAL EXAMINATION</b>			
<b>V</b>	Ventilators, heart lung machine, hemodialysis, lithotripsy, infant incubators X-rays- principles of generation, uses of X-rays- diagnostic still picture, fluoroscopy, angiography, endoscopy, diathermy. Basic principle of computed tomography, magnetic resonance imaging system and nuclear medicine system – radiation therapy. Ultrasonic imaging system - introduction and basic principle.	8	20%
<b>VI</b>	Instruments for clinical laboratory – test on blood cells – chemical tests - Electrical safety– physiological effects of electric current – shock hazards from electrical equipment – method of accident prevention, introduction to tele- medicine.	6	20%
<b>END SEMESTER EXAM</b>			

### QUESTION PAPER PATTERN:

Maximum Marks: 100

Exam Duration: 3Hourrs.

**Part A:** 8 compulsory questions.

One question from each module of Modules I - IV; and two each from Module V & VI.

Student has to answer all questions. (8 x5)=40

**Part B:** 3 questions uniformly covering Modules I & II. Student has to answer any 2 from the 3 questions: (2 x 10) =20. Each question can have maximum of 4 sub questions (a,b,c,d), if needed.

**Part C:** 3 questions uniformly covering Modules III & IV. Student has to answer any 2 from the 3 questions: (2 x 10) =20. Each question can have maximum of 4 sub questions (a,b,c,d), if needed.

**Part D:** 3 questions uniformly covering Modules V & VI. Student has to answer any 2 from the 3 questions: (2 x 10) =20. Each question can have maximum of 4 sub questions (a,b,c,d), if needed.



Course code	Course Name	L-T-P - Credits	Year of Introduction
EE332	Systems and Control laboratory	0-0-3-1	2016
<b>Prerequisite:</b> EE303 Linear control systems			
<b>Course Objectives</b> <ul style="list-style-type: none"> <li>To develop mathematical models for electrical systems, analyse the systems and implement compensators for systems based on system performance.</li> </ul>			
<b>List of Experiments:</b> <ol style="list-style-type: none"> <li>Predetermination and verification of frequency response characteristics of Lag and Lead networks.</li> <li>Transfer Function of AC and DC servomotors</li> <li>Step and frequency response of R-L-C circuit</li> <li>Study of P, PI and PID controllers. Response analysis of a typical system with different controllers, using process control simulator.</li> <li>Study of performance characteristics and response analysis of a typical temperature/ Flow/ Level control system.</li> <li>MATLAB: Use of control system Tool box for the Time domain and frequency domain methods of system analysis and design</li> <li>SIMULINK: Simulation and control of real time systems using SIMULINK</li> <li>Compensator design using Bode plot with MATLAB control system Tool box</li> <li>Simple experiments using Programmable Logic Controller- Realization of AND, OR logic, concept of latching, experiments with timers and counters- using ladder diagrams</li> <li>Study of various types of synchros (TX, TR &amp; TDX). Characteristics of transmitter, data transmission using TX-T R pair. Effect of TDX in data transmission.</li> <li>Realization of Lag &amp; lead compensator using active components</li> </ol>			
<b>End examination shall be based on design of a controller for the given system</b>			
<b>Course Outcome:</b> <p>After successful completion of this course, students will be able to:</p> <ol style="list-style-type: none"> <li>Develop mathematical models for servomotors and other electrical systems</li> <li>Performance analysis of different process control systems</li> <li>Performance analysis of different types of controllers</li> <li>Use MATLAB and SIMULINK to design and analyze simple systems and compensators</li> </ol>			



Course code	Course Name	L-T-P - Credits	Year of Introduction
EE334	Power Electronics and Drives Lab	0-0-3-1	2016
<b>Prerequisite:</b> EE305 Power electronics			
<b>Course Objectives</b> <ul style="list-style-type: none"> <li>Impart practical knowledge for the design and setup of different power electronic converters and its application for motor control</li> <li>Simulate the various power electronics converters, AC drives and DC drives.</li> </ul>			
<b>List of Exercises/Experiments:</b> ( 12 experiments are mandatory)			
<b>HARDWARE EXPERIMENTS:</b> <ol style="list-style-type: none"> <li>Static characteristics of SCR Aim: Determine latching current, holding current and static characteristics of SCR</li> <li>R and RC firing circuits Aim: Design and set up R and RC firing circuits and observe waveforms across load resistance and SCR</li> <li>UJT Trigger circuit with Single phase controlled Rectifier Aim: Design &amp; Set up UJT Triggering Circuit and observe waveforms across load resistance, SCR, capacitance and pulse transformer output.</li> <li>Line Synchronised Triggering Circuits Aim: Design and set-up line synchronized Ramp Trigger and Digital Trigger circuits and observe the waveforms</li> <li>Static characteristics of MOSFET Aim: Plot the characteristics of a Power MOSFET</li> <li>AC Voltage Controller using TRIAC Aim: Set a 1-phase AC voltage controller &amp; observe waveforms across load resistance, TRIAC and capacitor for different firing angles</li> <li>Single Phase fully Controlled SCR Bridge circuit Aim: Set up a 1-phase full converter with RL load &amp; with and without freewheeling diode</li> <li>Single-phase half bridge/full bridge inverter using power MOSFET/IGBT Aim: Design and set up a single phase half-bridge/full-bridge inverter and observe the waveforms across load and firing pulses.</li> <li>Single-phase sine PWM inverter with LC filter Aim: Design and set up a single phase sine PWM inverter with LC filter using microcontroller</li> <li>Chopper controlled DC motor Aim: Control the speed of a DC motor using a step-down chopper</li> <li>Speed control of 3-phase induction motor Aim: Control the speed of 3-phase induction motor using V/f control</li> <li>IGBT based three phase PWM Inverter Aim: Set up a 3-phase PWM Inverter with RL load and observe the waveforms</li> <li>Closed Loop Control of Single Phase Fully Controlled Rectifier Aim: Design and set-up a closed loop control circuit for a 1ph Fully Controlled Rectifier such that it keeps the load voltage constant irrespective of the load variations (use R load)</li> </ol>			
<b>SIMULATION EXPERIMENTS:</b> <ol style="list-style-type: none"> <li>Simulation of 1-phase fully-controlled and half-controlled rectifier fed separately excited DC motor Aim: Simulate 1-phase fully-controlled and half-controlled rectifier fed SEDC motor and observe the speed, torque, armature current, armature voltage, source current waveforms and find the THD in source current and input power factor.</li> </ol>			

15. Simulation of closed loop speed control of DC motor with different control schemes (PID, hysteresis current control, Fuzzy, ANFIS etc)
16. Simulation of open loop or closed loop speed control of 3-phase induction motor using V/f control and using sine PWM
17. Design and simulation of buck, boost and buck-boost converters
18. Simulation of Dual Converter – 4 quadrant operation – separately excited DC motor
19. Simulation of Regenerative Braking – Bidirectional Power Transfer
20. Simulation of Switched Mode Rectifiers – keeping load voltage constant irrespective of line and load variations – closed loop circuit simulation

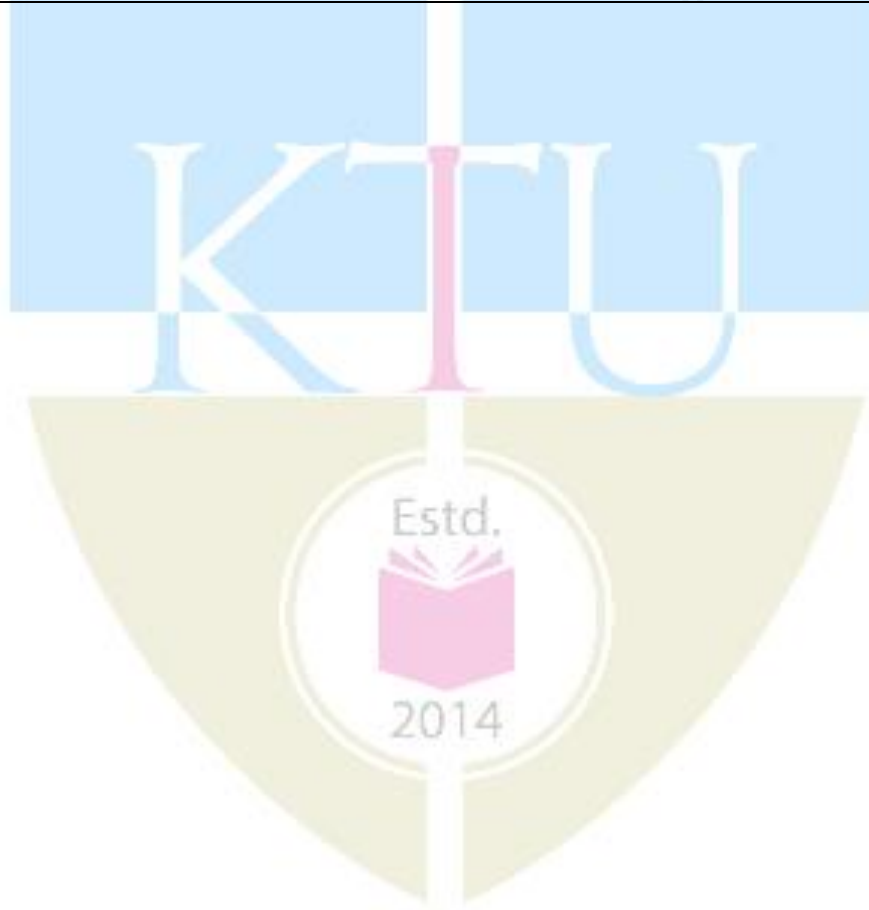
**Minimum of EIGHT hardware experiments and FOUR simulation experiments from the above list are to be done**

**Expected outcome.**

- Students will be able to design, setup and analyse various power electronic converters and apply these converters for the implementation of various motor control applications.

**Text Book:**

- 1) L. Umanand, *Power Electronics – Essentials & Applications*, Wiley-India
- 2) Mohan, Undeland, Robbins, *Power Electronics, Converters, Applications & Design*, Wiley-India
- 3) Muhammad H. Rashid, *Power Electronics Circuits, Devices and Applications*, Pearson Education



Course code	Course Name	L-T-P - Credits	Year of Introduction
<b>**352</b>	<b>Comprehensive Examination</b>	<b>0-1-1-2</b>	<b>2016</b>
<b>Prerequisite : Nil</b>			
<b>Course Objectives</b> <ul style="list-style-type: none"> <li>To assess the comprehensive knowledge gained in basic courses relevant to the branch of study</li> <li>To comprehend the questions asked and answer them with confidence.</li> </ul>			
<b>Assessment</b> <p><b>Oral examination</b> – To be conducted by the college (@ three students/hour) covering all the courses up to and including V semester– 50 marks</p> <p><b>Written examination</b> - To be conducted by the Dept. on the date announced by the University– common to all students of the same branch – objective type ( 1 hour duration)– 50 multiple choice questions ( 4 choices) of 1 mark each covering the six common courses of S1&amp;S2 and six branch specific courses listed – questions are set by the University - no negative marks – 50 marks.</p> <p><i>Note:</i> Both oral and written examinations are mandatory. But separate minimum marks is not insisted for pass. If a students does not complete any of the two assessments, grade I shall be awarded and the final grade shall be given only after the completion of both the assessments. The two hours allotted for the course may be used by the students for discussion, practice and for oral assessment.</p>			
<b>Expected outcome.</b> <ul style="list-style-type: none"> <li>The students will be confident in discussing the fundamental aspects of any engineering problem/situation and give answers in dealing with them</li> </ul>			

